

KIT 257 JEL/JRC

line 7, delete "turn".

Page 5, line 18, delete "adjust" and insert therefor --align--, and delete "adjacent a work line".

**IN THE CLAIMS:**

Please amend the following claims:

1. (Amended twice) A floor working machine comprising a self-propelled vehicle body including a working implement for treating a floor surface, characterized by;

U-turn control means for causing said self-propelled vehicle body to make a U-turn automatically to [adjust] align said working implement to a work line adjacent a work line treated before said U-turn;

spin turn control means for causing said self-propelled vehicle body to make a spin turn automatically to [adjust] align said working implement to work line [adjacent to work line] treated before said spin turn; and

running control means for automatically controlling said U-turn control means and said spin turn control means in response to input signals for causing said self-propelled vehicle body to make selectively a U-turn under control of said U-turn control means and a spin turn under control of said spin turn control means.

11. (Amended twice) A floor working machine comprising a self-propelled vehicle body including running wheels, wheel drive means, a working implement for treating a floor surface, and means for driving said working implement, characterized by;

control means for controlling said self-propelled vehicle body and including;